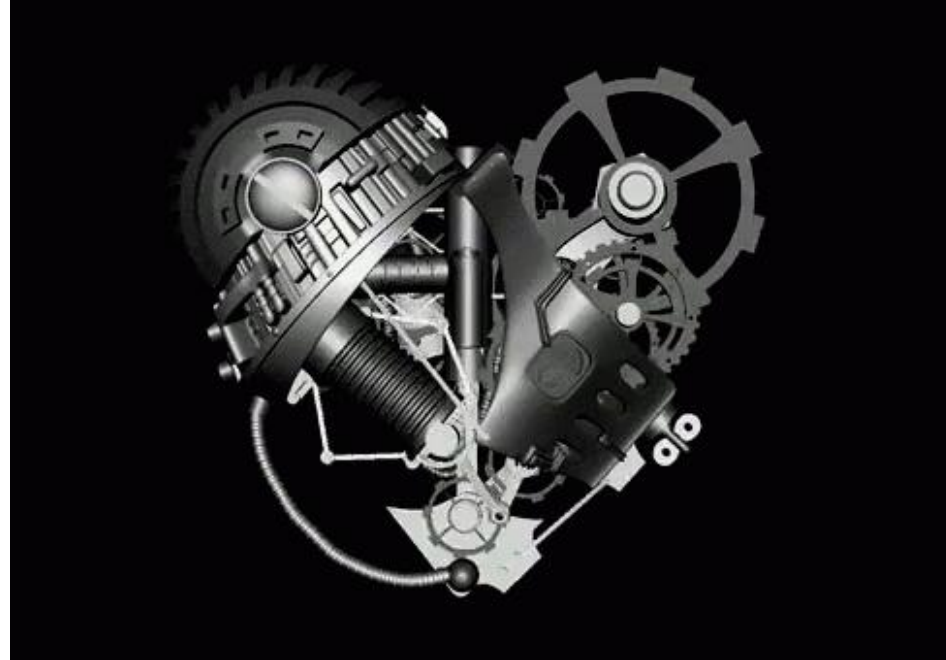


Grade 12 – Physics



Unit 1: Mechanics

Chapter 1: Energy

Prepared & presented by: **Mr. Mohamad Seif**



OBJECTIVES

- 1 Recall the definition of work of a constant force**

Recall Work of a constant force

Force causes Displacement  **Work is done**



Recall Work of a constant force

The work done by constant force:

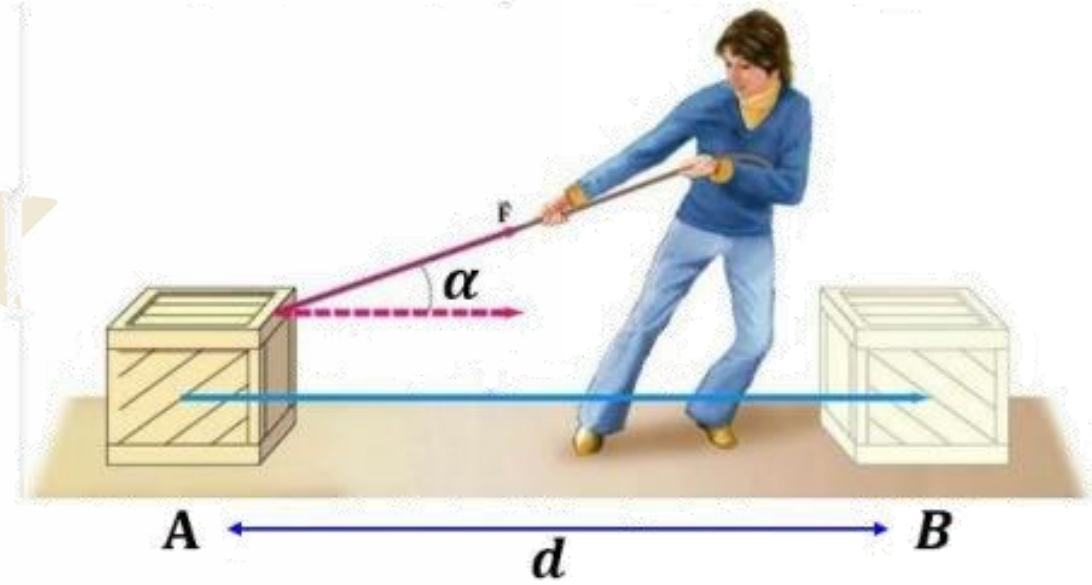
$$W_{\vec{F}} = F \times AB \times \cos(\alpha)$$

$W_{\vec{F}}$: work done by the force,
expressed in **Joule J**.

F : applied force, expressed in **Newton N**

AB : is the distance covered by the box, expressed in **meter m**.

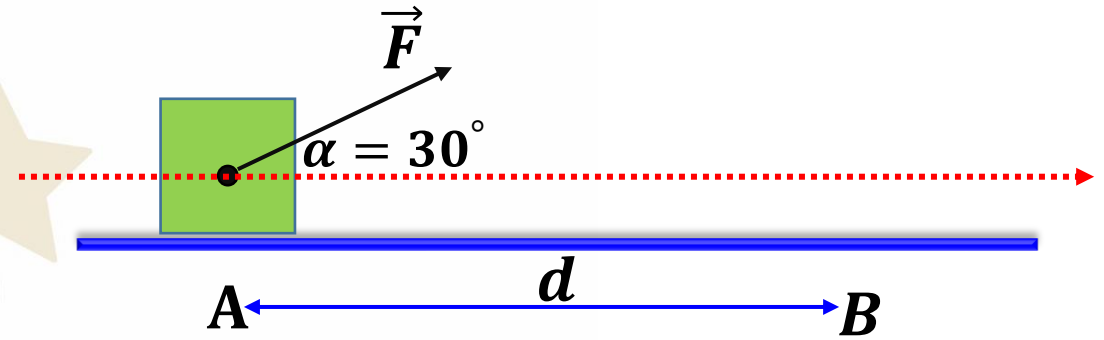
α : angle between the force and the displacement, expressed in degree.



Work done by constant force

Application 1:

A box of mass $m = 750g$ slides on a rough surface AB.



The box moves under the action of a force $F = 0.75N$ making an angle $\alpha = 30^\circ$ with the horizontal.

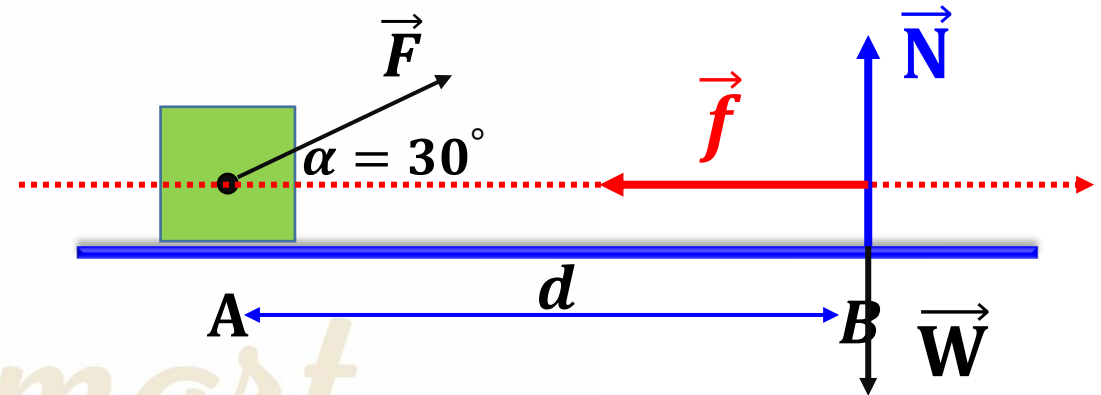
The magnitude of friction between the box and the surface is $f_r = 2N$.

Given $AB = 150cm$ and $g = 10N/kg$.

Work done by constant force

$m = 0.75\text{Kg}$; $F = 0.75\text{N}$; $\alpha = 30^\circ$; $f_r = 2\text{N}$; $AB = 1.5\text{m}$ and $g = 10\text{N/kg}$.

1) Name all the forces acting on the block, then represent the forces on the figure.



The forces are:

- Weight: \vec{W}
- Normal: \vec{N}
- Friction: \vec{f}
- Tractive force: \vec{F}

Work done by constant force

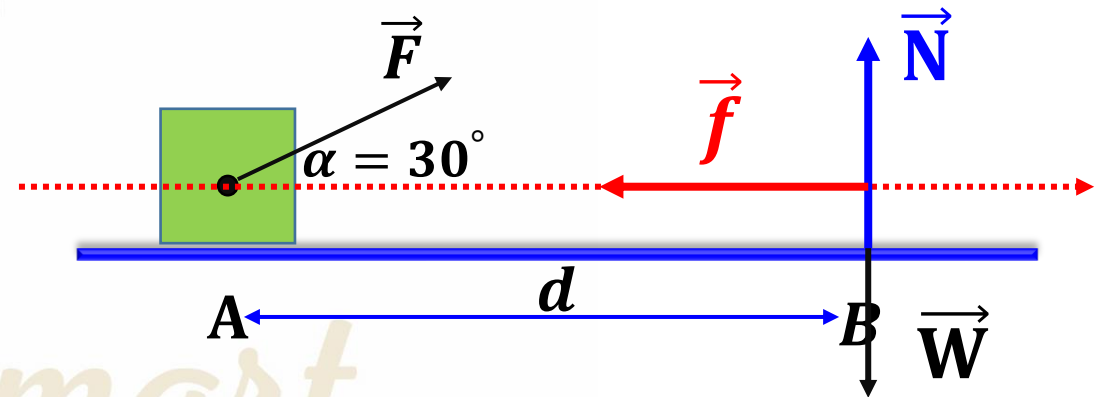
$m = 0.75\text{Kg}$; $F = 0.75\text{N}$; $\alpha = 30^\circ$; $f_r = 2\text{N}$; $AB = 1.5\text{m}$ and $g = 10\text{N/kg}$.

2) Calculate the work done by each force.

Work done by normal force:

$$W_{\vec{N}} = N \times d \times \cos(\vec{N}; d)$$

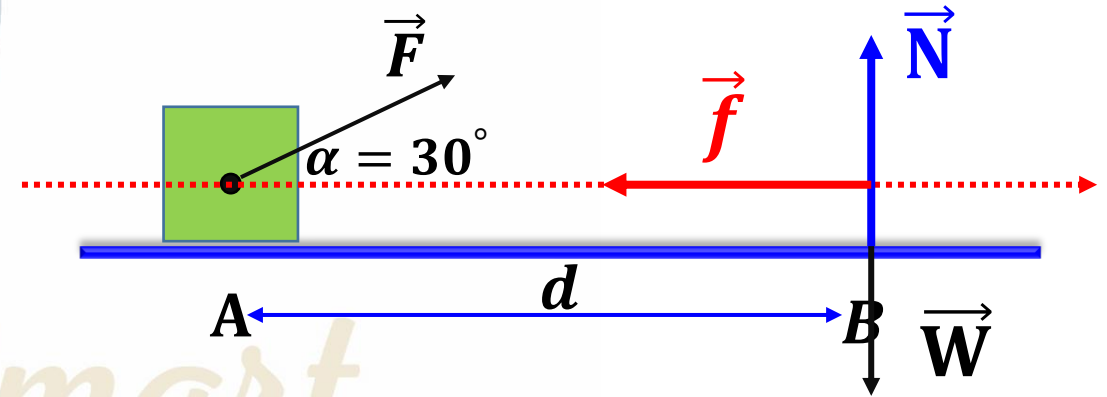
$$W_{\vec{N}} = N \times AB \times \cos(90) \quad \Rightarrow \quad W_{\vec{N}} = 0\text{J}$$



Work done by constant force

$m = 0.75\text{Kg}$; $F = 0.75\text{N}$; $\alpha = 30^\circ$; $f_r = 2\text{N}$; $AB = 1.5\text{m}$ and $g = 10\text{N/kg}$.

2) Calculate the work done by each force.



Work done by friction force:

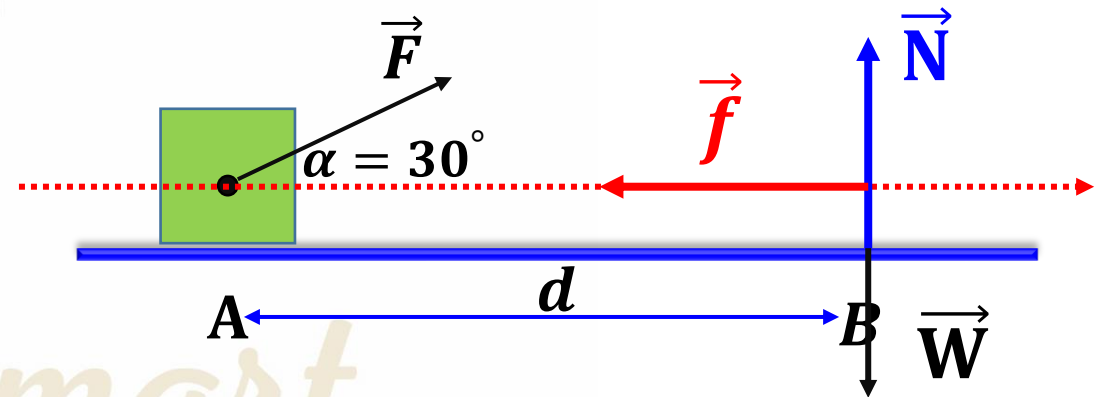
$$W_{\vec{f}} = f \times d \times \cos(\vec{f}; d) \quad W_{\vec{f}} = 2 \times 1.5 \times (-1)$$

$$W_{\vec{f}} = f \times AB \times \cos(180) \quad W_{\vec{f}} = -3J$$

Work done by constant force

$m = 0.75\text{Kg}$; $F = 0.75\text{N}$; $\alpha = 30^\circ$; $f_r = 2\text{N}$; $AB = 1.5\text{m}$ and $g = 10\text{N/kg}$.

2) Calculate the work done by each force.



Work done by tractive force :

$$W_{\vec{F}} = F \times d \times \cos(\vec{F}; d)$$

$$W_{\vec{F}} = 0.97\text{J}$$

$$W_{\vec{F}} = 0.75 \times 1.5 \times \cos(30)$$

Work done by constant force

$m = 0.75\text{Kg}$; $F = 0.75\text{N}$; $\alpha = 30^\circ$; $f_r = 2\text{N}$; $AB = 1.5\text{m}$ and $g = 10\text{N/kg}$.

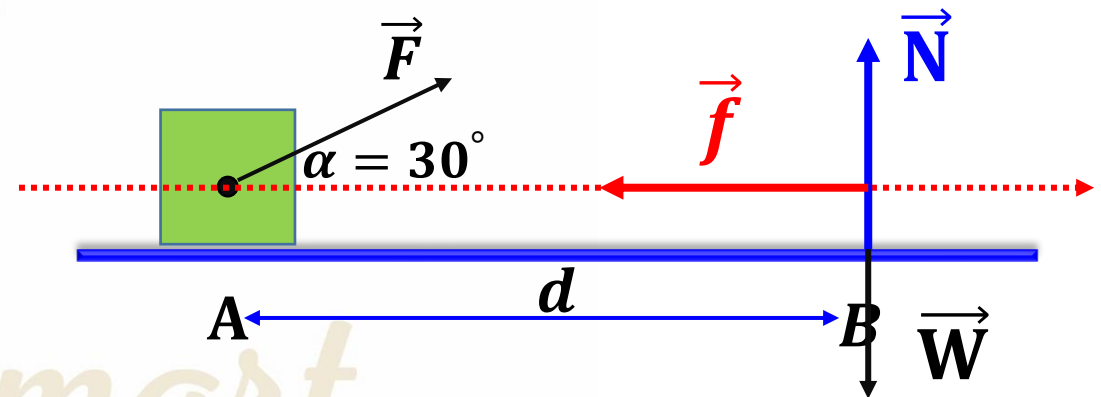
2) Calculate the work done by each force.

Work done by weight :

$$W_{\vec{W}} = mg(h_i - h_f)$$

$$W_{\vec{W}} = 0.75 \times 1.5(0 - 0)$$

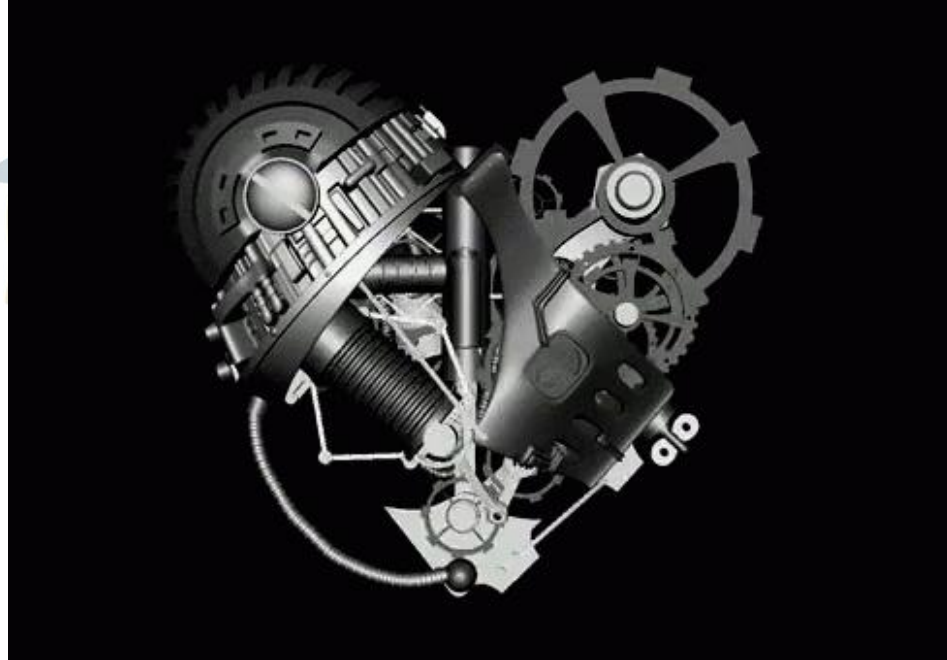
$$W_{\vec{W}} = 0\text{J}$$



The End



Grade 12 – Physics



Unit 1: Mechanics

Chapter 1: Energy

Prepared & presented by: **Mr. Mohamad Seif**



OBJECTIVES

- 1 Recall the definition of energy and its types.
- 2 Determine the Kinetic energy

ACADEMY

Energy

Energy: Is the ability to do work.

Object has energy  **Work can be done**

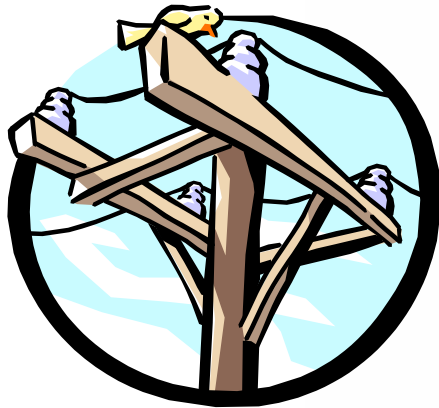
Energy, as work, is expressed in Joules (J).

- **Energy exists in many forms.**
- **Energy can be transferred from one object to another.**
- **Energy can be changed from one form to another.**
- **Energy cannot be created or destroyed.**

Energy

Forms of energy

Electric



Radiant



Mechanical



Nuclear



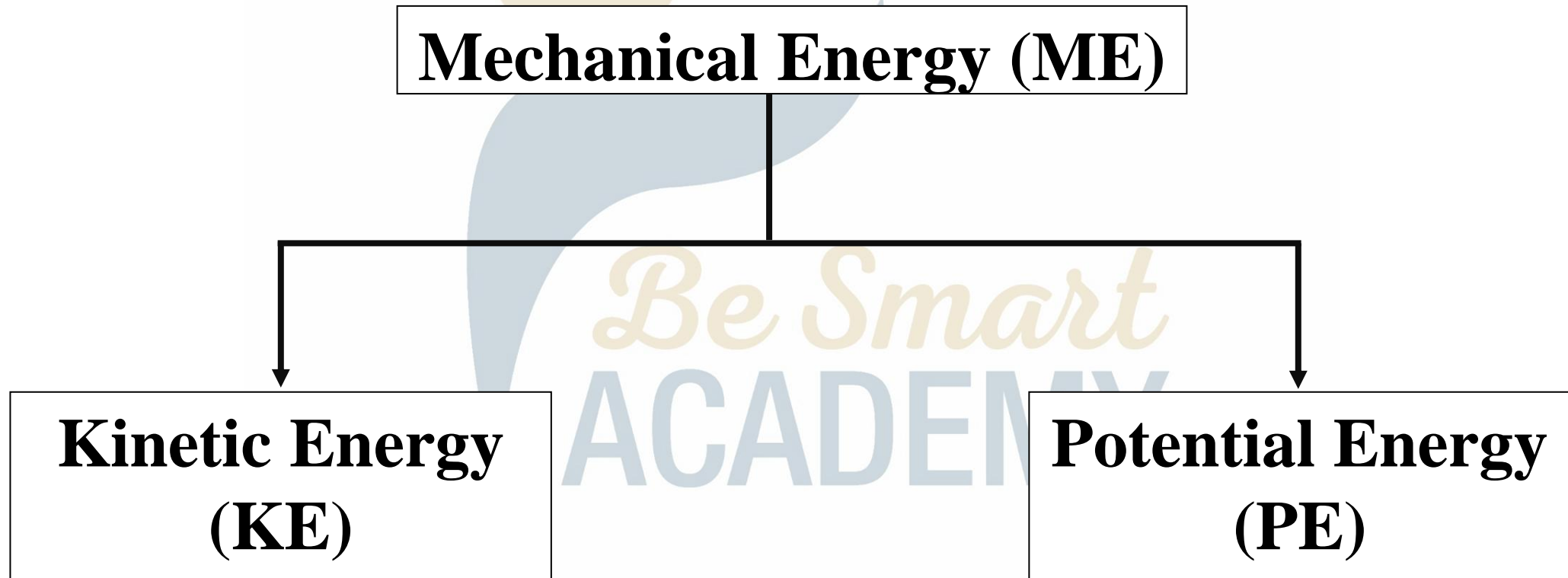
Thermal

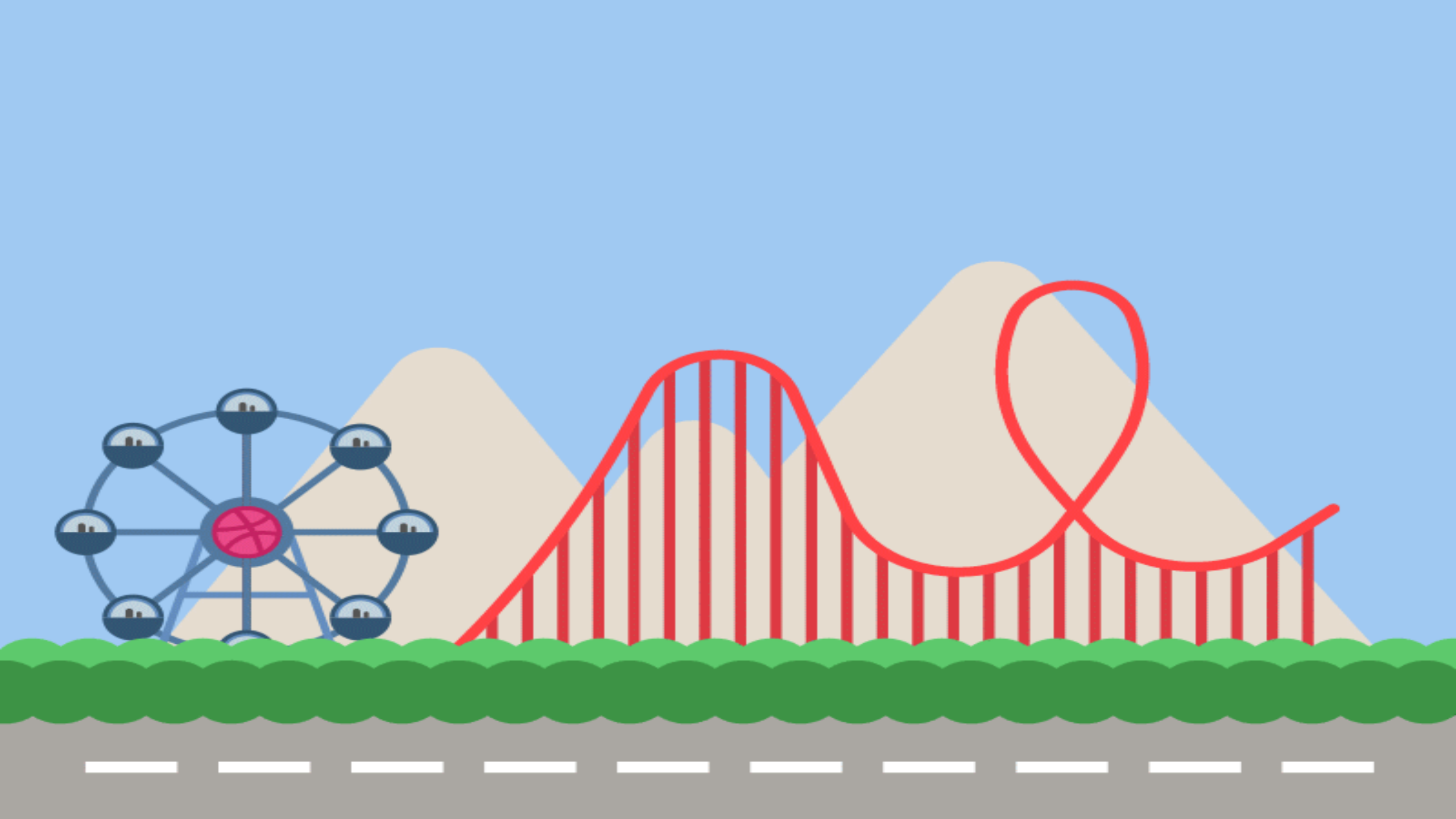


In this lesson we will study
mechanical energy

Energy

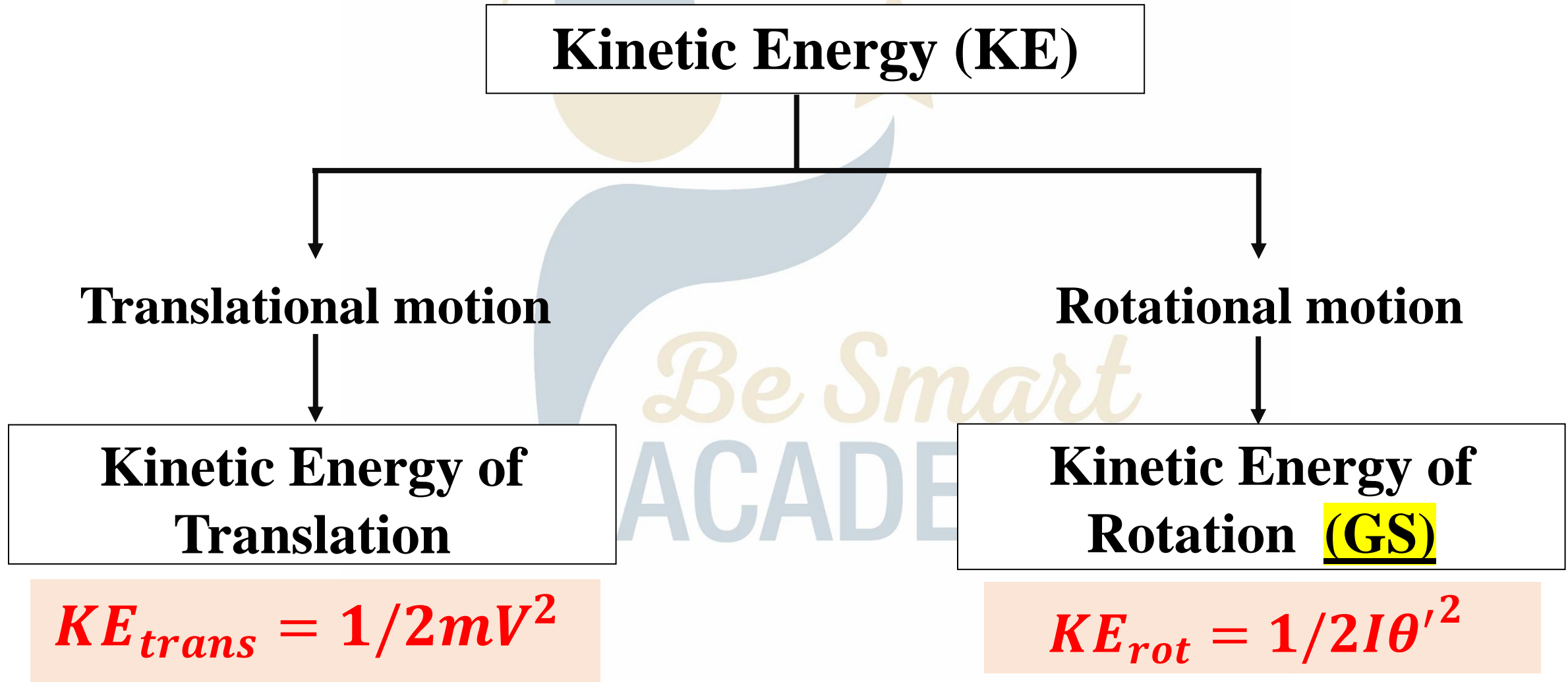
Mechanical Energy (ME): of a system is the sum of its **macroscopic kinetic energy KE** and **macroscopic potential energy PE**:





Kinetic Energy (KE)

Kinetic Energy (KE): Energy possessed by a body due to its motion.



Kinetic Energy (KE)

Kinetic Energy of Translation (KE_{trans}):

$$KE_{trans} = \frac{1}{2} m V^2$$

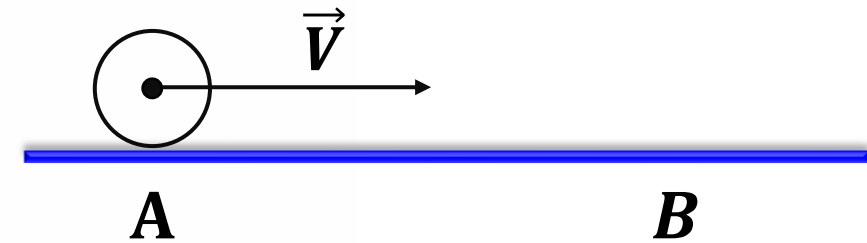
- m : mass of the body, expressed in (kg).
- V : The velocity of the body, expressed in m/s.
- KE_{trans} : Kinetic energy, expressed in (J).



Kinetic Energy (KE)

Application 2:

A ball of mass $m = 2\text{Kg}$ starts its motion from rest from A and reaches B with a speed $v = 3\text{m/s}$ as shown in the figure.



Calculate the kinetic energy of the ball at A and at B.

$$KE_A = 1/2 m V^2$$

$$KE_A = 0.5 \times 2 \times (0)^2$$

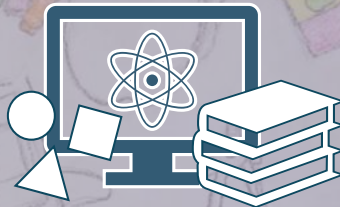
$$KE_A = 0\text{J}$$

$$KE_B = 1/2 m V^2$$

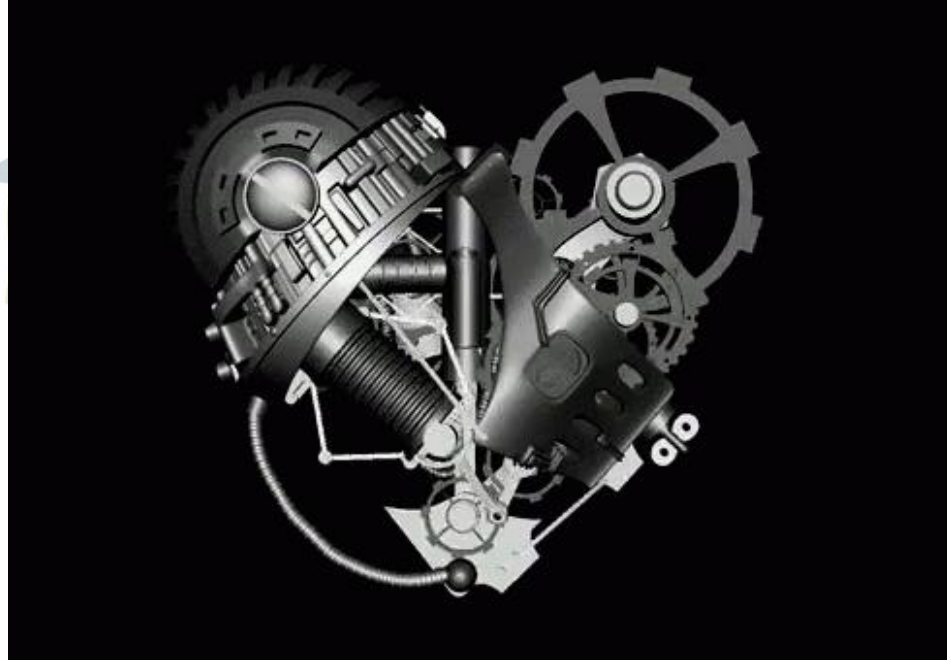
$$KE_B = 0.5 \times 2 \times (3)^2$$

$$KE_B = 9\text{J}$$

The End



Grade 12 – Physics



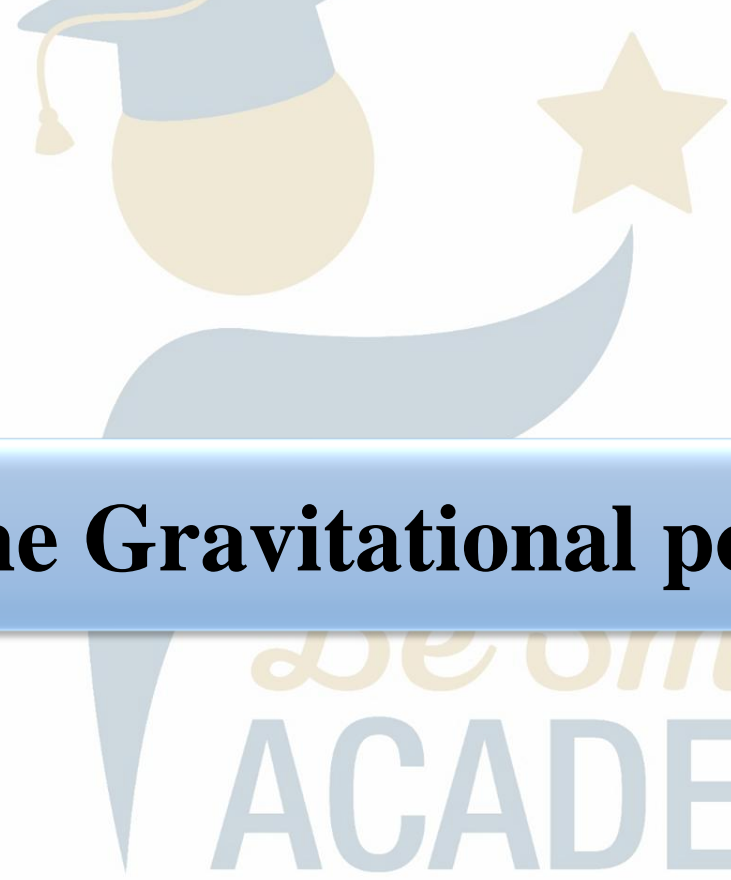
Unit 1: Mechanics

Chapter 1: Energy

Prepared & presented by: **Mr. Mohamad Seif**



OBJECTIVES



- 1 **Determine the Gravitational potential energy**

Potential Energy (PE)

Potential Energy (PE): is a form of energy stored in the body

Potential Energy (PE)

```
graph TD; PE[Potential Energy (PE)] --> GPE[Gravitational potential energy]; PE --> EPE[Elastic potential energy]; GPE --> GPE_formula["PE_g = mgh"]; EPE --> EPE_formula["PE_e = 1/2 kx^2"];
```

**Gravitational
potential energy**

$$PE_g = mgh$$

**Elastic potential
energy**

$$PE_e = \frac{1}{2} kx^2$$

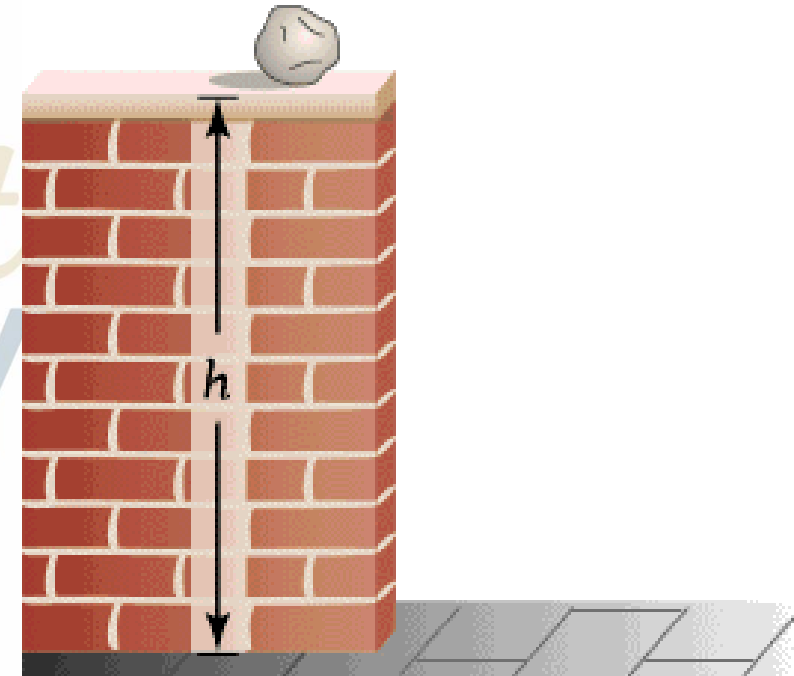
Gravitational Potential Energy (GPE)

Gravitational Potential Energy (GPE):

Gravitational Potential Energy is the energy stored in a body due to the **relative position** of the system with respect to the **reference**

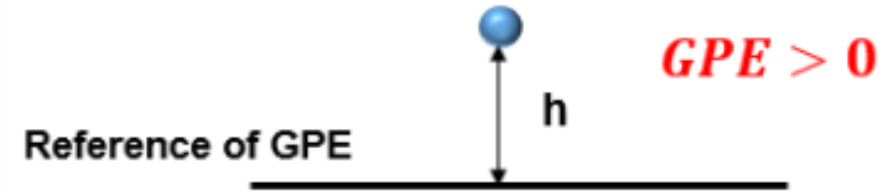
$$PE_g = mgh$$

- ***m***: mass of the body, expressed in kg.
- ***g***: gravity, $g=10\text{N/kg}$.
- ***h***: height of the body from the reference expressed in m



Gravitational Potential Energy (GPE)

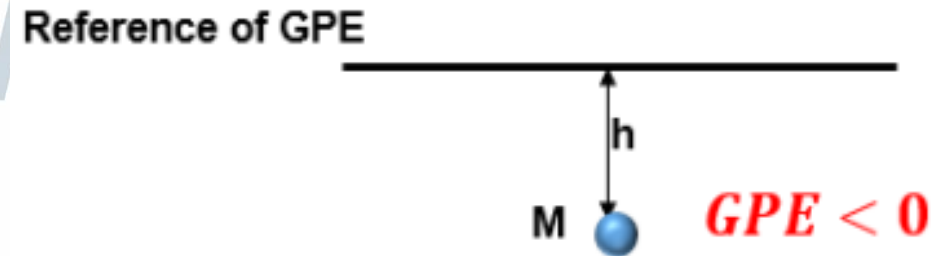
If the body above reference, then $h > 0$



If the body on reference, then $h = 0$



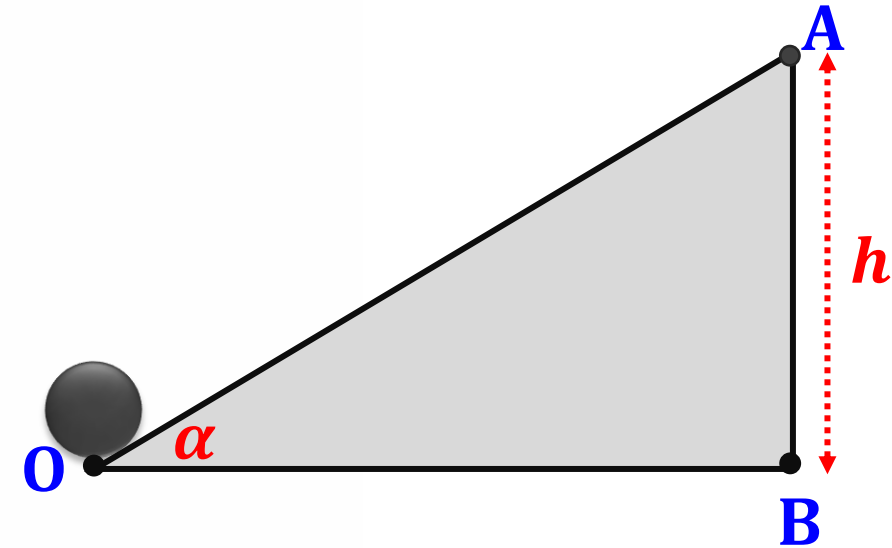
If the body below reference, then $h < 0$



Gravitational Potential Energy (GPE)/ inclined plane

Application 4:

A ball (S) of mass $m = 1.2\text{Kg}$ moves up an inclined plane making an angle $\alpha = 30^\circ$ with the horizontal starting from the bottom O.



The ball reaches point A at a height h from the ground, where $OA = 1.5\text{m}$

Take the horizontal line passing through B as a reference level for gravitational potential energy. Given $g = 10\text{N/kg}$
Calculate *GPE* of the system (ball-earth) at point A.

Gravitational Potential Energy (GPE)/ inclined plane

$$m = 1.2\text{Kg}; OA = 1.5\text{m}; \alpha = 30; g = 10\text{N/kg};$$

The gravitation potential energy is:

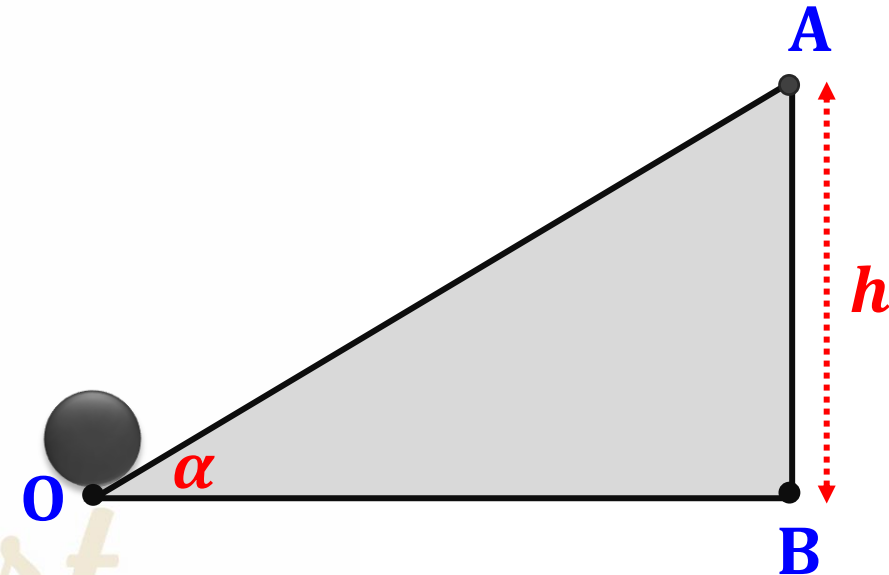
$$GPE_A = mgh$$

For the triangle AOB: $\sin\alpha = \frac{\text{opp}}{\text{hyp}}$

$$\Rightarrow \sin\alpha = \frac{h}{OA} \rightarrow h = OA \sin\alpha$$

$$\Rightarrow GPE = mgh = mg(OA \sin\alpha)$$

$$\Rightarrow GPE = 1.2 \times 10 \times 1.5 \times \sin 30 \quad \Rightarrow \quad GPE = 9\text{J}$$



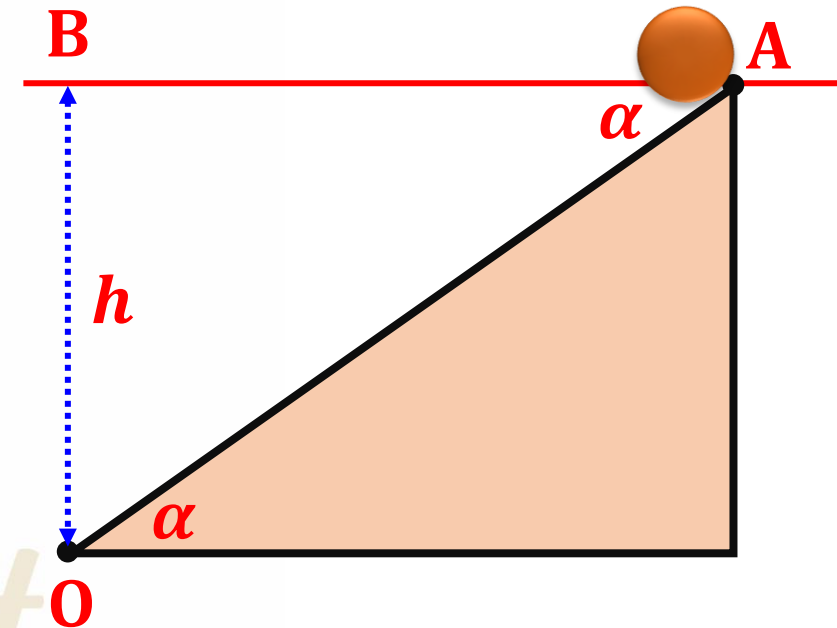
Gravitational Potential Energy (GPE)/ inclined plane

Application 5:

A ball of mass $m = 2\text{kg}$ at the top A of an inclined plane making an angle $\alpha = 60^\circ$ with the horizontal.

The ball moves down and reaches point O, where $AO = 90\text{cm}$.

The horizontal plane passing through A is a reference level for gravitational potential energy. Given $g = 10\text{N/kg}$
Calculate GPE of the system (ball-earth) at point O.



Gravitational Potential Energy (GPE)/ inclined plane

$$m = 2\text{Kg}; AO = 0.9\text{m}; \alpha = 60^\circ; g = 10\text{N/kg}$$

The gravitational potential energy is:

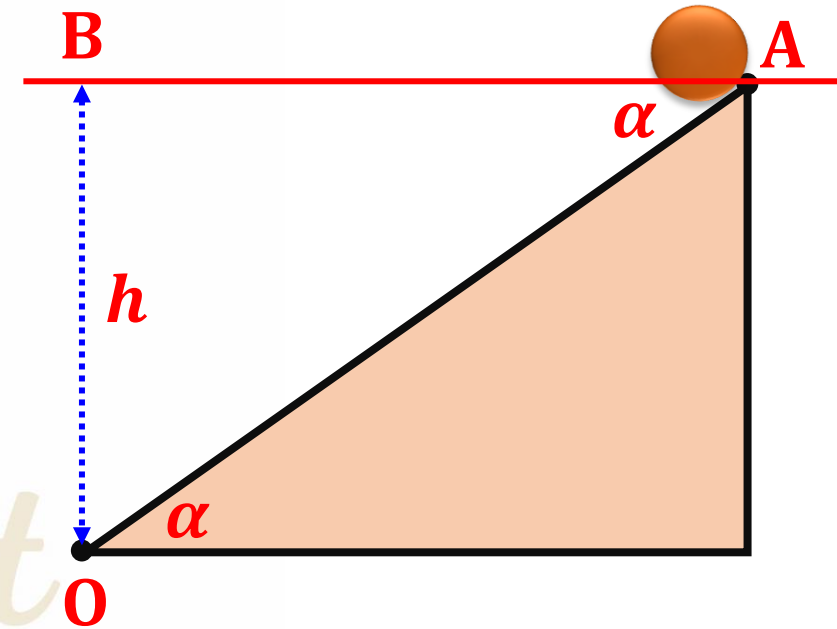
$$GPE = mgh$$

For the triangle AOB: $\sin\alpha = \frac{\text{opp}}{\text{hyp}}$

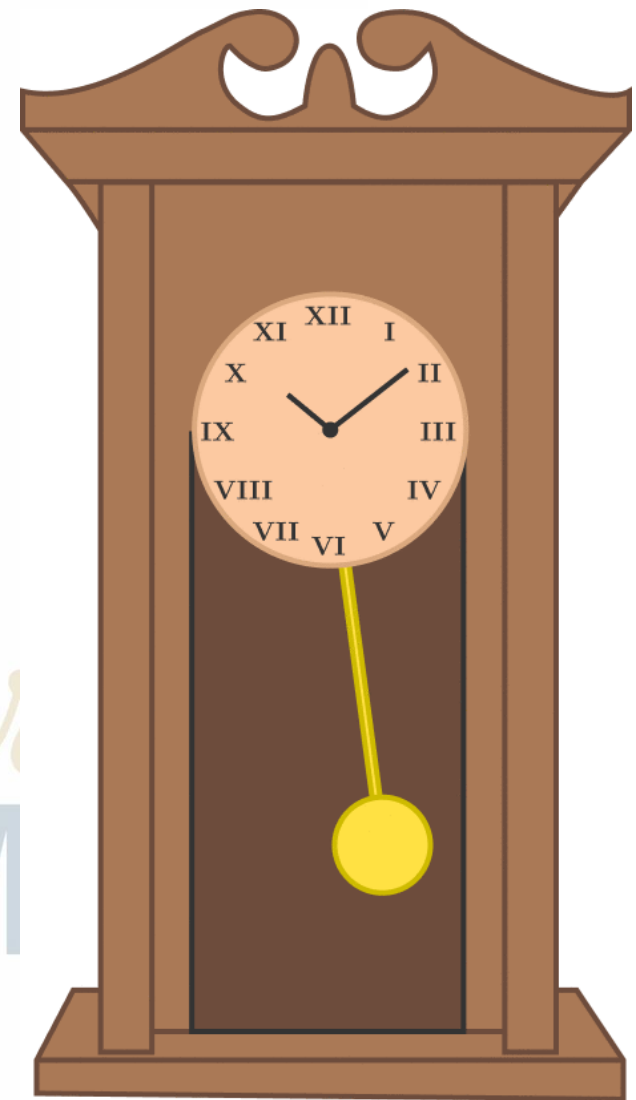
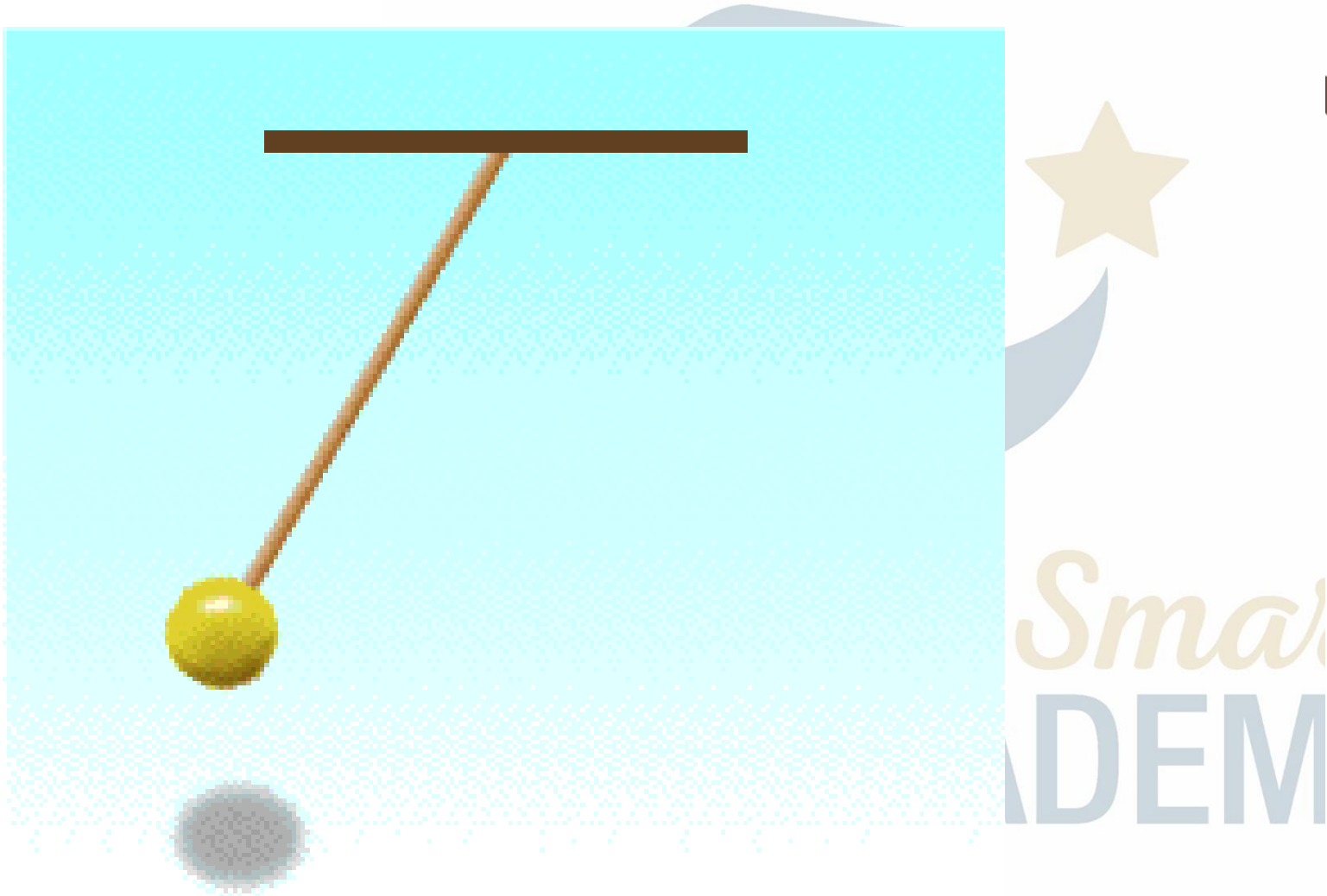
$$\Rightarrow \sin\alpha = \frac{-h}{AO} \rightarrow h = -AO\sin\alpha$$

$$\Rightarrow GPE = mg(-AO\sin\alpha)$$

$$\Rightarrow GPE = 2 \times 10 \times (-0.9 \times \sin 60) \Rightarrow GPE = -15.6\text{J}$$



Gravitational Potential Energy/ Pendulum



Gravitational Potential Energy (GPE)/ Pendulum

Gravitational potential energy at point A at a height h above the reference level:

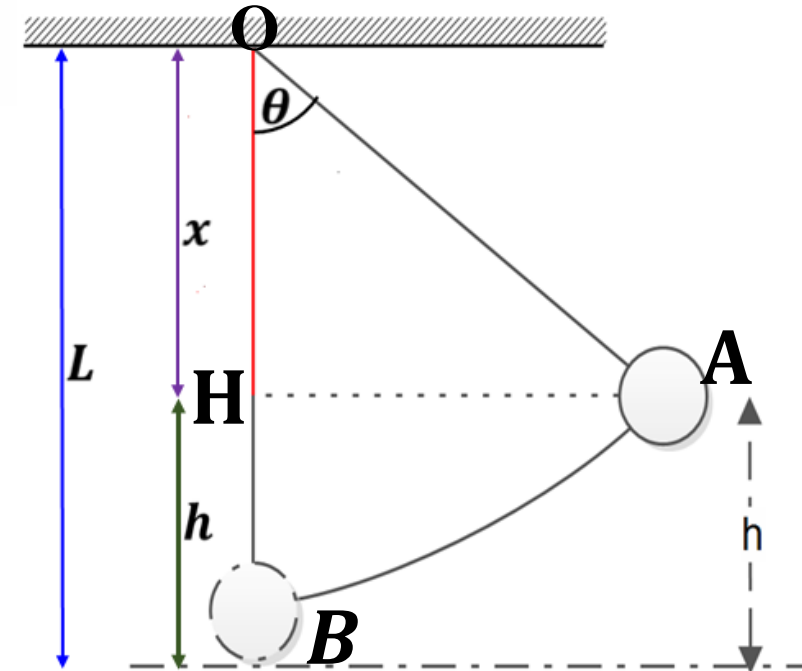
The gravitational potential energy:

$$GPE_A = mgh$$

$$L = h + x \rightarrow h = (L - x)$$

For the triangle AOH: $\cos\theta = \frac{\text{adj}}{\text{hyp}} = \frac{x}{L}$ $\Rightarrow x = L\cos\theta$

$$\Rightarrow h = (L - x) = L - L\cos\theta \Rightarrow h = L(1 - \cos\theta)$$



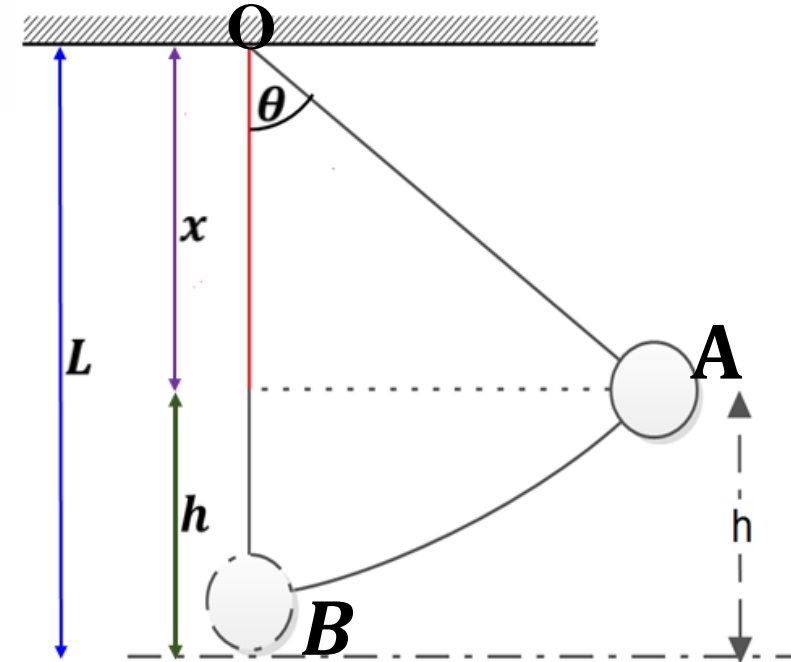
Gravitational Potential Energy (GPE)/ Pendulum

Application 6:

A pendulum is formed of a massless and inextensible string of length $L = 90\text{cm}$, having one of its ends O fixed to a support while the other end carries a particle (S) of mass $m = 200\text{ g}$.

The pendulum is shifted from its equilibrium position to point A making an angle $\theta = 30^\circ$.

The horizontal plane passing through B is a reference level for gravitational potential energy. Given $g = 10\text{N/kg}$.



Gravitational Potential Energy (GPE)/ Pendulum

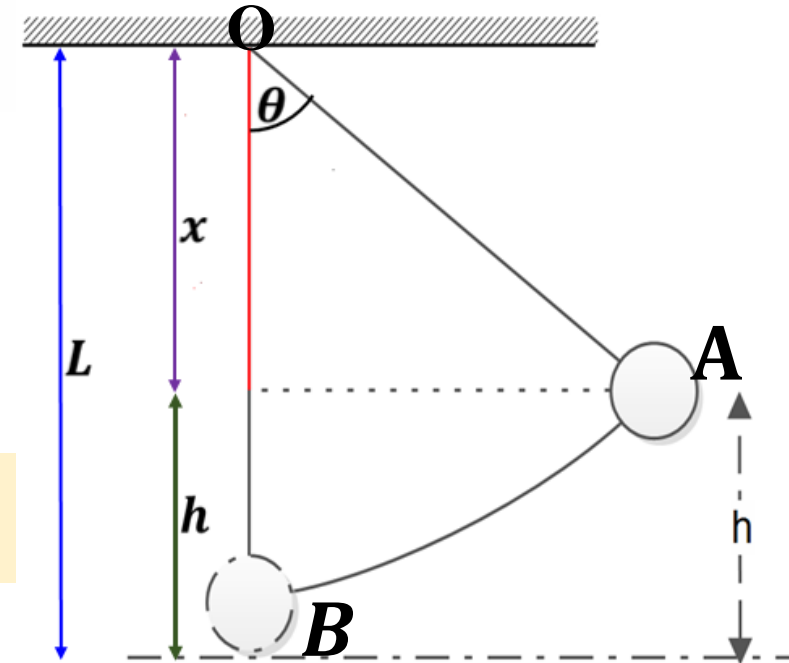
Calculate GPE of the system (pendulum-earth) at point A when it making angle $\theta = 30^\circ$ with the equilibrium position.

$$m = 2\text{kg}; L = 0.9\text{m}; \theta = 30; g = 10\text{N/kg}$$

$$GPE_A = mgh = mgL(1 - \cos\theta)$$

$$\Rightarrow GPE_A = 2 \times 10 \times 0.9(1 - \cos 30)$$

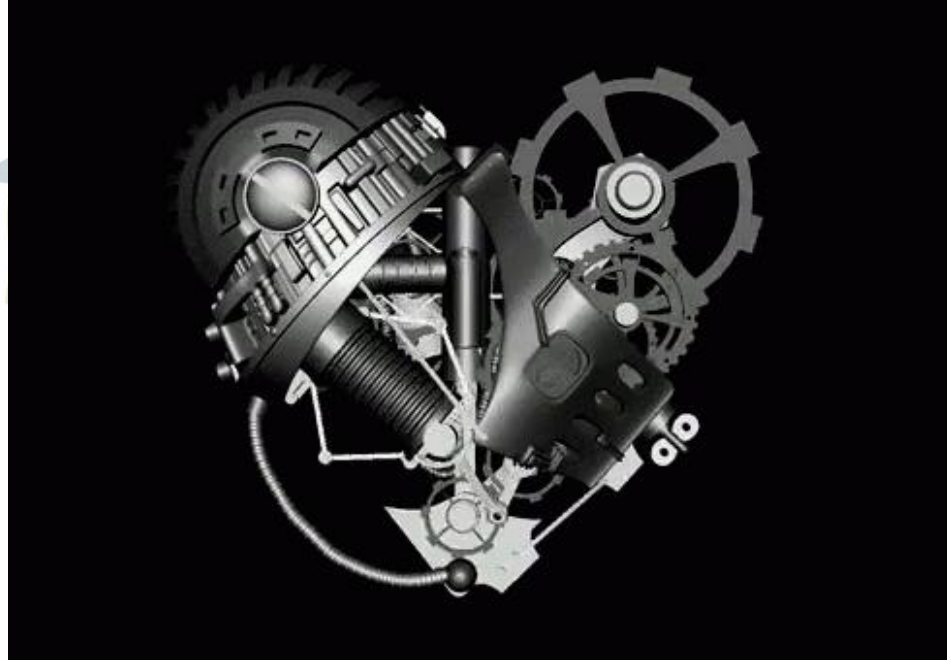
$$\Rightarrow PE_g = 2.4\text{J}$$



The End



Grade 12 – Physics



Unit 1: Mechanics

Chapter 1: Energy

Prepared & presented by: **Mr. Mohamad Seif**



OBJECTIVES



- 1 **Determine the Elastic Potential energy of a particle**

ACADEMY

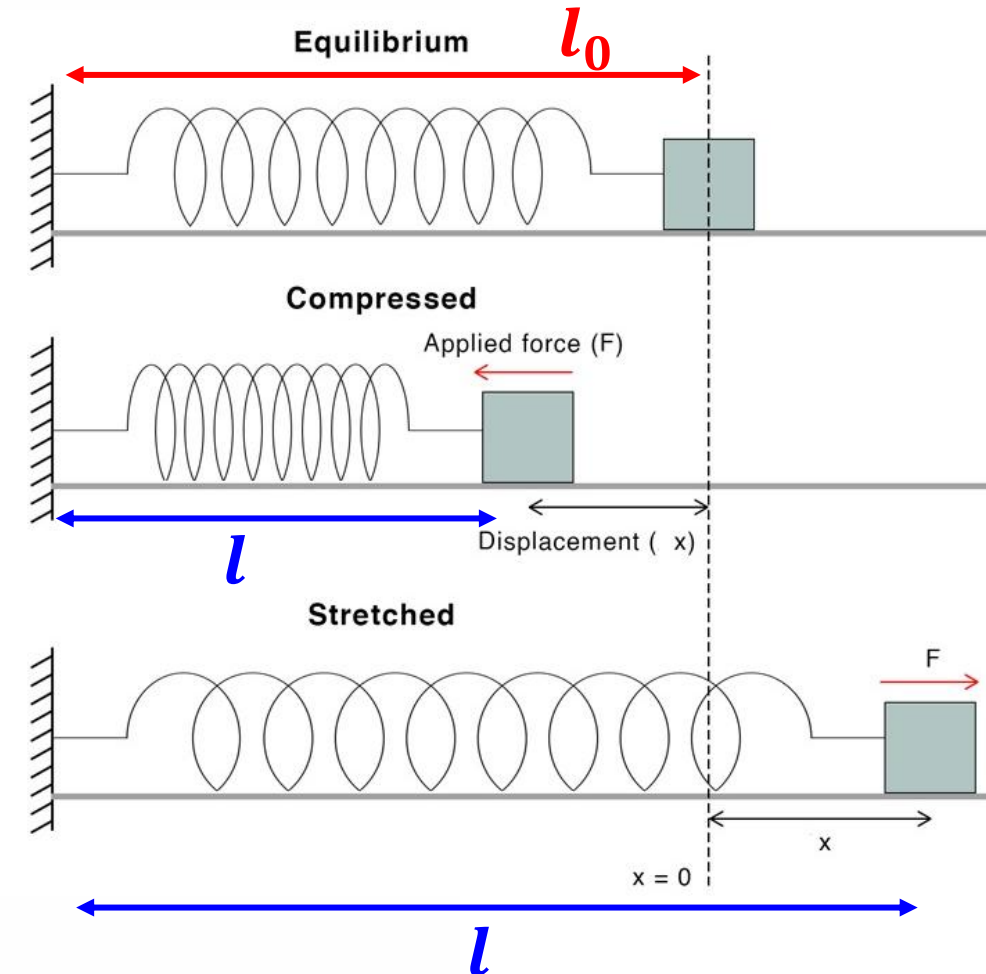
Elastic Potential Energy (EPE)

Elastic Potential Energy (EPE): is stored in elastic objects such as rubber bands, springs, ...

$$EPE = \frac{1}{2} kx^2$$

l_0 : initial length

$$x = \begin{cases} l - l_0 & (\text{elongation}) \\ l_0 - l & (\text{compression}) \end{cases}$$



Elastic Potential Energy (EPE)

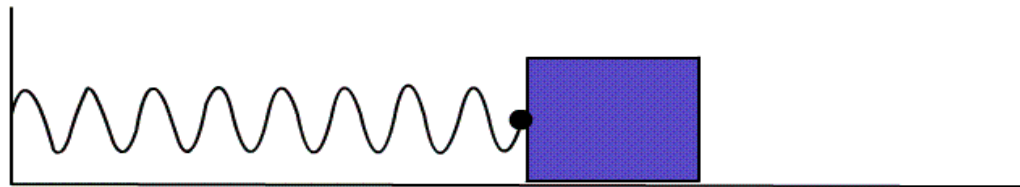
$$EPE = \frac{1}{2} kx^2$$

- ***EPE***: elastic potential energy, expressed in J.
- ***K***: spring constant (stiffness) expressed in N/m.
- ***x***: The compression or elongation of the spring, expressed in m.

De Smart
ACADEMY

Elastic Potential Energy (EPE)

$$EPE = \frac{1}{2} kx^2$$



Horizontal spring



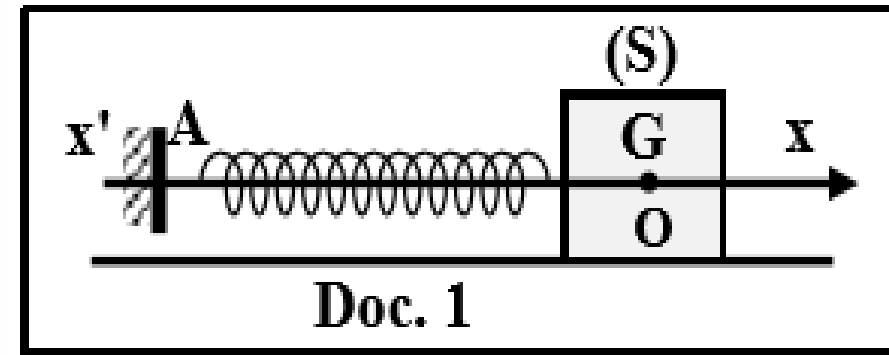
Vertical spring

Elastic Potential Energy (EPE)

Application 7:

Consider a box (S) of mass $m = 500\text{g}$ is connected to a spring (R) of free length $l_0 = 25\text{cm}$.

The stiffness of the spring is $k = 20\text{N/m}$
The spring is elongated by a distance x and become has a length $l = 35\text{cm}$.



1. Calculate the variation in length Δl .
2. Calculate the elastic potential energy stored in the spring when it is elongated by $x = \Delta L$

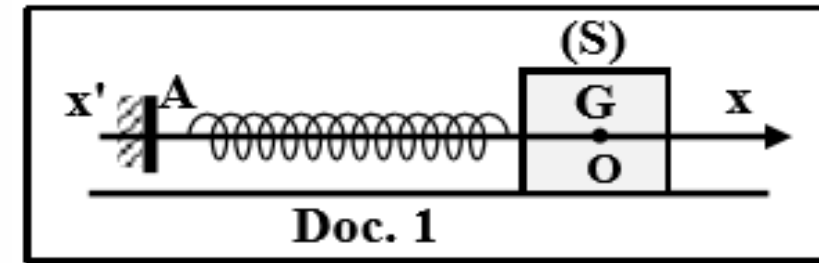
Elastic Potential Energy (EPE)

$m = 500\text{g}; l_0 = 25\text{cm}; k = 20\text{N/m}; l = 35\text{cm}.$

1. Calculate the variation in length Δl .

$$x = \Delta L = l - l_0$$

$$\Rightarrow x = 35 - 25 \Rightarrow x = 10\text{cm} = 0.1\text{m}$$



2. Calculate the elastic potential energy stored in the spring when it is elongated by $x = \Delta L$

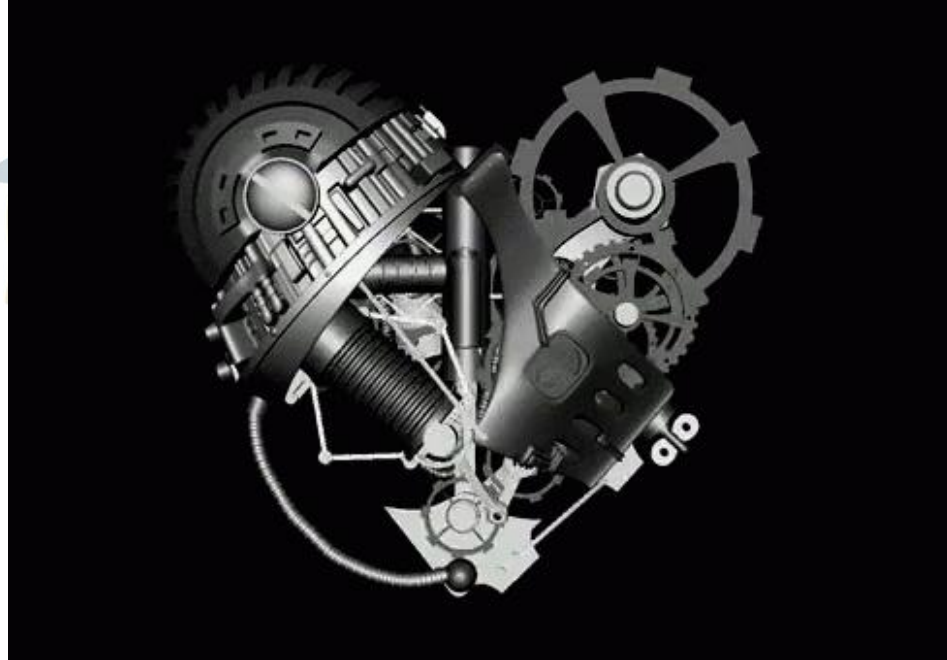
$$\text{EPE} = \frac{1}{2}kx^2 \Rightarrow \text{EPE} = 0.5 \times (20) \times (0.1)^2$$

$$\Rightarrow \text{EPE} = 0.1\text{J}$$

The End



Grade 12 – Physics



Unit 1: Mechanics

Chapter 1: Energy

Prepared & presented by: **Mr. Mohamad Seif**



OBJECTIVES

- 1 **Determine the mechanical energy of a particle**
- 2 **Determine the internal energy of a particle**
- 3 **Determine the total energy of a system**

Mechanical Energy (ME)

The Mechanical Energy of a system at a certain point is:
the sum of kinetic energy and potential energy of a system at a
certain point, expressed in J

$$\text{ME} = \text{KE} + \text{PE}_g + \text{PE}_e$$

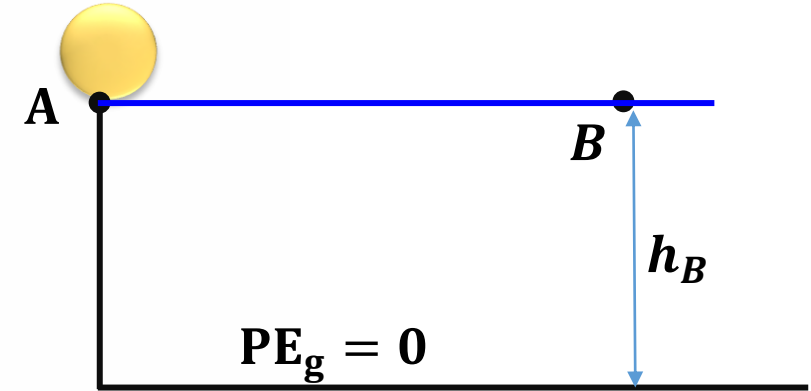
Be Smart
ACADEMY

Mechanical Energy (ME)

Application 8:

A particle (S) of mass of $m = 1.25\text{Kg}$ starts its motion from rest from A.

The particle reaches point B, 3.1m above the ground with a speed of 2.5m/s.



Take the ground as reference level for gravitational potential energy.
Given $g = 10\text{N/kg}$.

- 1) Calculate the mechanical energy of the system[(S)-earth] at point A.
- 2) Calculate the mechanical energy of the system[(S)-earth] at point B

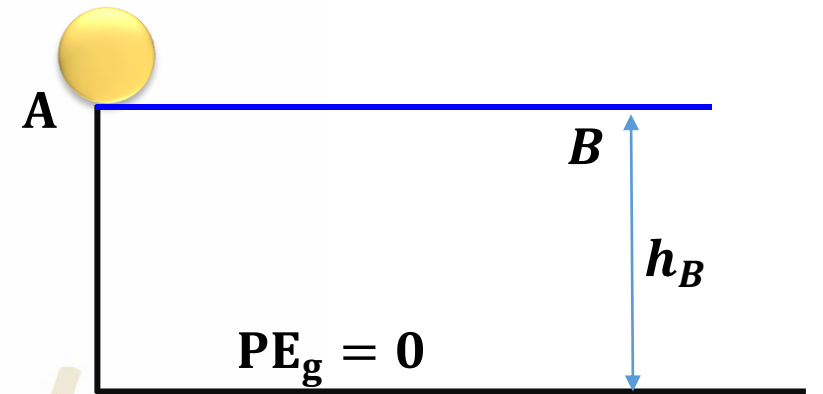
Mechanical Energy (ME)

$m = 1.25\text{kg}; h_A = h_B = 3.1\text{m}; V_B = 2.5\text{m/s}; g=10\text{N/kg}.$

1) Calculate the mechanical energy of the system[(S)-earth] at point A.

$$ME_A = KE_A + (GPE)_A$$

$$ME_A = \frac{1}{2}mV_A^2 + mgh_A$$



$$\Rightarrow ME_A = 0.5 \times 1.25 \times (0)^2 + 1.25 \times 10 \times 3.1$$

$$\Rightarrow ME_A = 0 + 38.75 \quad \Rightarrow \text{ME} = 38.75\text{J}$$

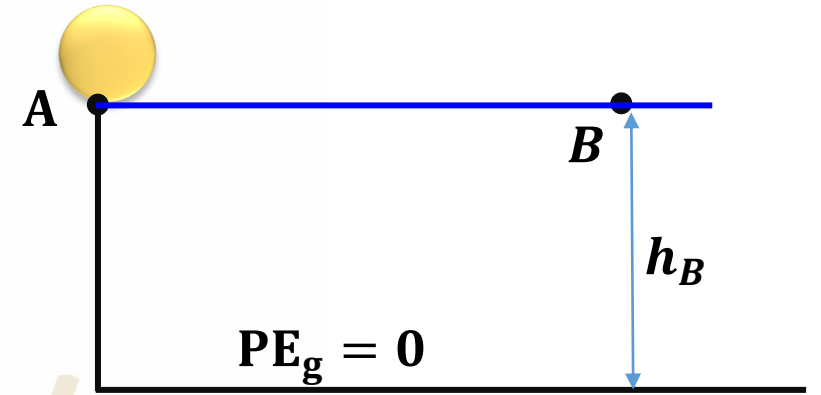
Mechanical Energy (ME)

$$m = 1.25\text{kg}; h_A = h_B = 3.1\text{m}; V_B = 2.5\text{m/s}; g=10\text{N/kg}.$$

2) Calculate the mechanical energy of the system[(S)-earth] at point B.

$$ME_B = KE_B + (GPE)_B$$

$$ME_B = \frac{1}{2}mV_B^2 + mgh_B$$



$$\Rightarrow ME_B = 0.5 \times 1.25 \times (2.5)^2 + 1.25 \times 10 \times 3.1$$

$$\Rightarrow ME_A = 3.9 + 38.75 \Rightarrow ME = 42.65\text{J}$$

Mechanical Energy: $ME = KE + PE$

Kinetic (KE) (motion)

Potential (PE) (position)

Translation

$$(KE_{tran} = 1/2mV^2)$$

Gravitational
($GPE = mgh$)

Elastic (EPE)
 $= 1/2kx^2$

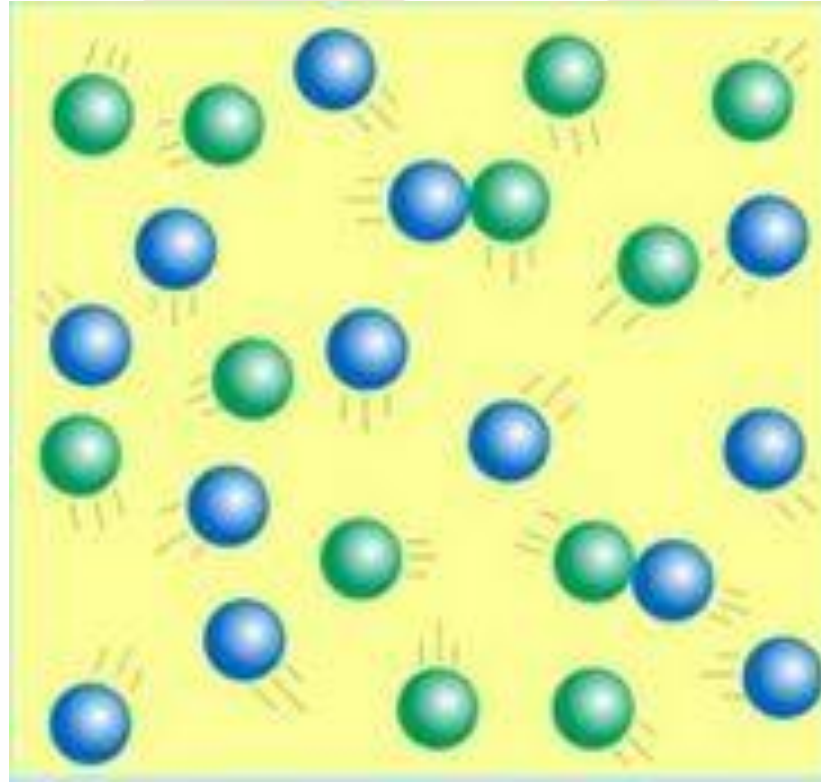
Rotation (GS)

$$(KE_{rot} = 1/2I\theta'^2)$$

Be Smart
ACADEMY

Internal Energy (Thermal energy): U

Internal Energy (U): is defined as the energy due to the random, disordered motion of molecules of a body

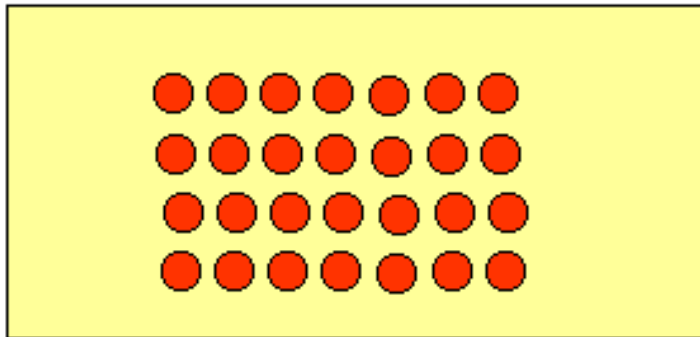


Internal Energy (Thermal energy): U

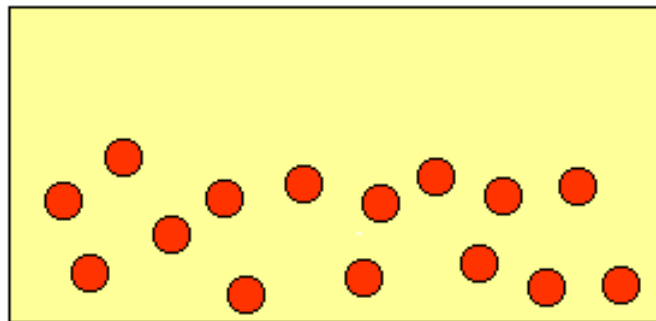
$$U = KE_{Microscopic}(\text{change of temperature}) + PE_{Microscopic}(\text{change of state})$$



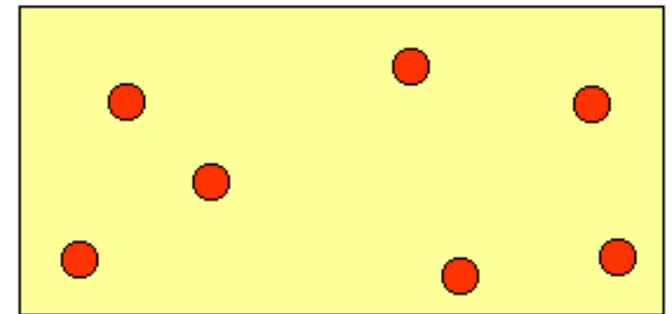
Solid



Liquid



Gas



Total Energy of the system (E)

Total Energy = Mechanical Energy + Internal Energy (Thermal)
Energy – isolated system: system does not exchange energy with surrounding

The total energy is conserved:

$$E = ME + U = \text{constant}$$

➡ $\Delta E = \Delta ME + \Delta U = 0$

➡ $\Delta U = -\Delta ME$



Total Energy

```
graph TD; TE[Total Energy] --> ME[Mechanical Energy]; TE --> IE[Internal Energy]; ME --> KE[Kinetic energy]; ME --> PE[Potential Energy]; KE --> T[Translation]; KE --> R["Rotation (GS)"]; PE --> G[Gravitational]; PE --> E[Elastic];
```

A hierarchical flowchart showing the classification of energy. At the top is 'Total Energy', which branches into 'Mechanical Energy' and 'Internal Energy'. 'Mechanical Energy' further branches into 'Kinetic energy' and 'Potential Energy'. 'Kinetic energy' branches into 'Translation' and 'Rotation (GS)'. 'Potential Energy' branches into 'Gravitational' and 'Elastic'. The background features a faint watermark of a graduation cap and a star, and the text 'Be Smart ACADEMY'.

Mechanical Energy

Internal Energy

Kinetic energy

Potential Energy

Translation

Rotation (GS)

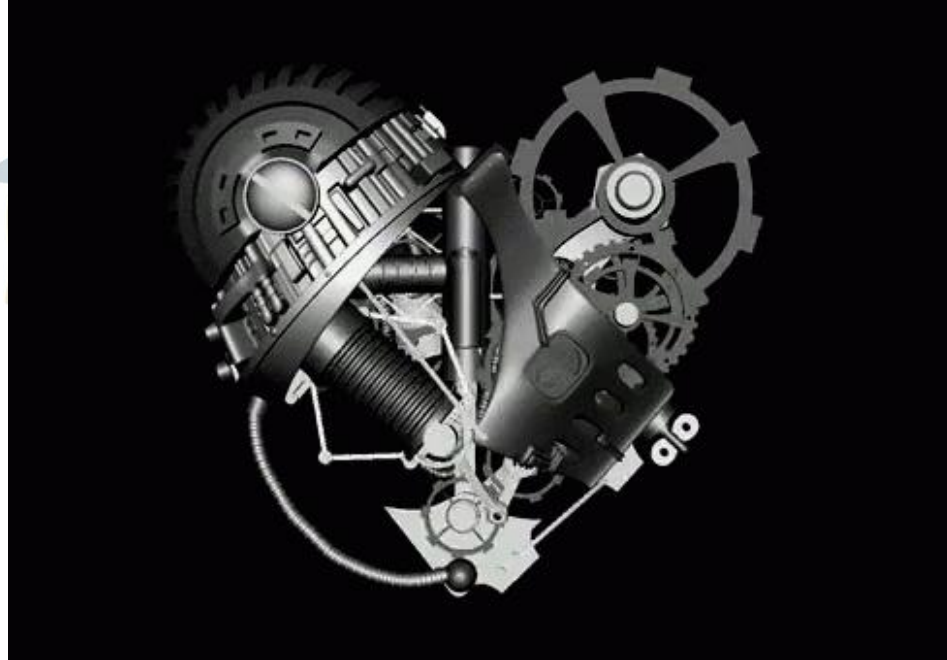
Gravitational

Elastic

The End



Grade 12 – Physics



Unit 1: Mechanics

Chapter 1: Energy

Prepared & presented by: **Mr. Mohamad Seif**



OBJECTIVES

- 1 Apply the principle of conservation of ME energy**
- 2 Apply the principle of non-conservation of ME energy**

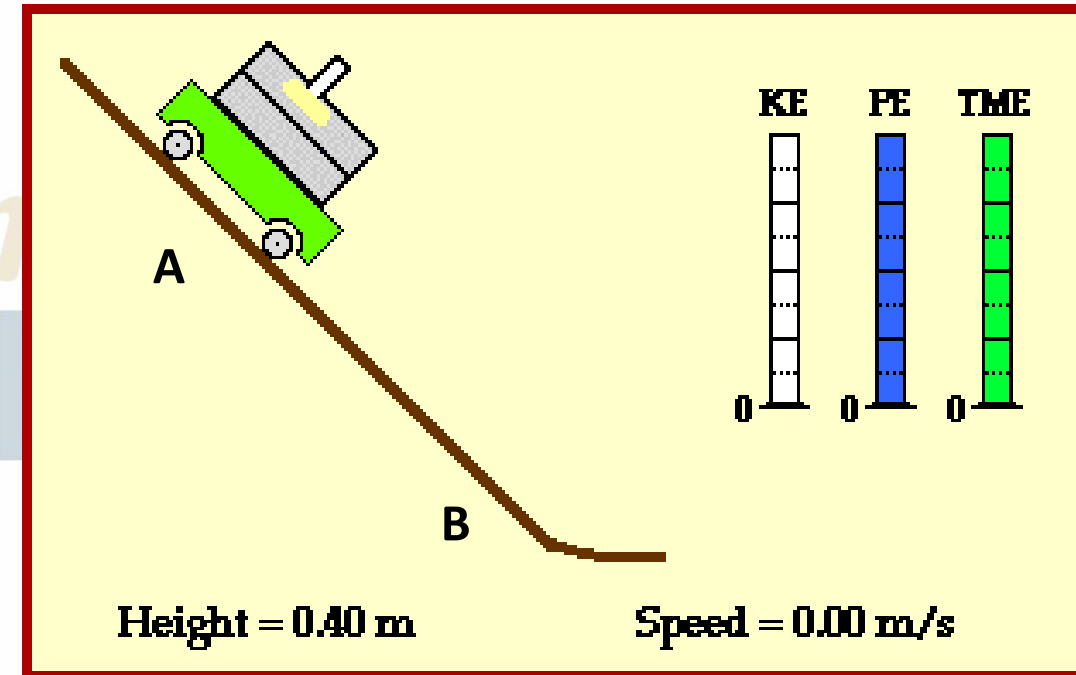
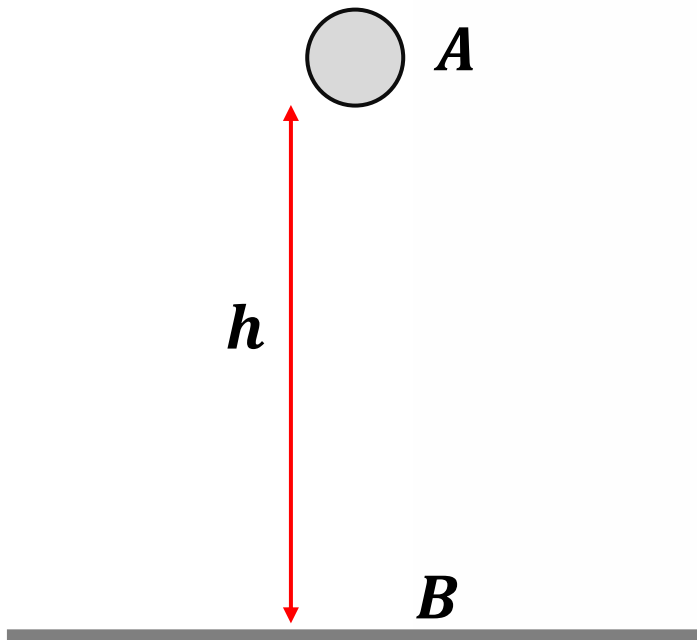
VACADEMY

Conservation of Mechanical Energy

A body moves from point **A** to point **B**. The mechanical energy of the system is conserved if:

The non-conservative forces (friction, air resistance, braking force, traction forces, damping force...) **are zero or neglected.** (ex: $f_r = 0$).

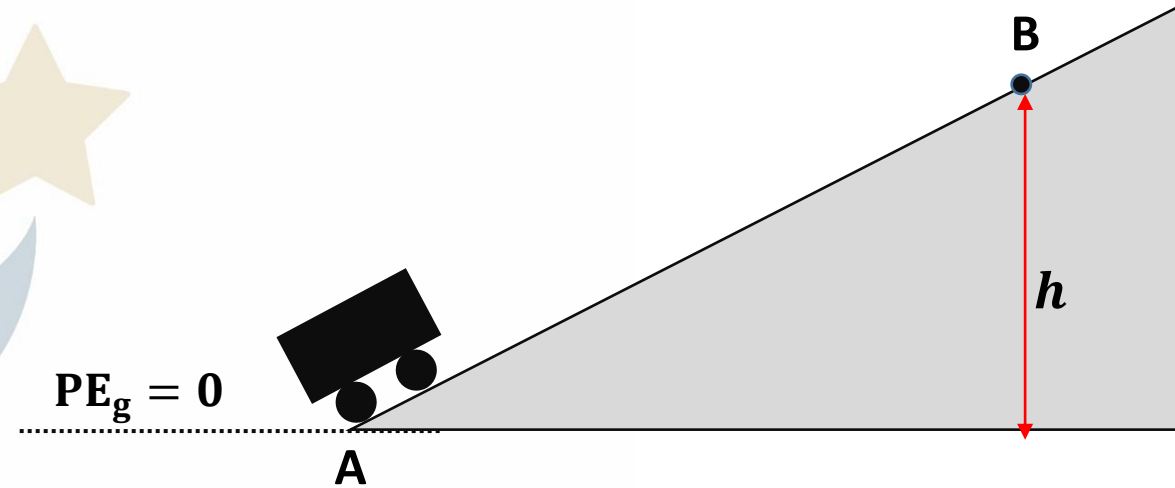
$$ME_A = ME_B$$



Conservation of Mechanical Energy

Application 9:

A car considered as a particle of mass 500kg starts with a speed of 20m/s from the bottom A of an inclined plane making an angle $\alpha = 30^\circ$ with the horizontal.



The car cuts 35.1m reaches point B at a height h above the ground with a speed of 7m/s .

1. Calculate the mechanical energy of the system [car-earth] at point A.
2. Calculate the mechanical energy of the system [car-earth] at point B.
3. Compare the mechanical energy at A and B, then deduce

Conservation of Mechanical Energy

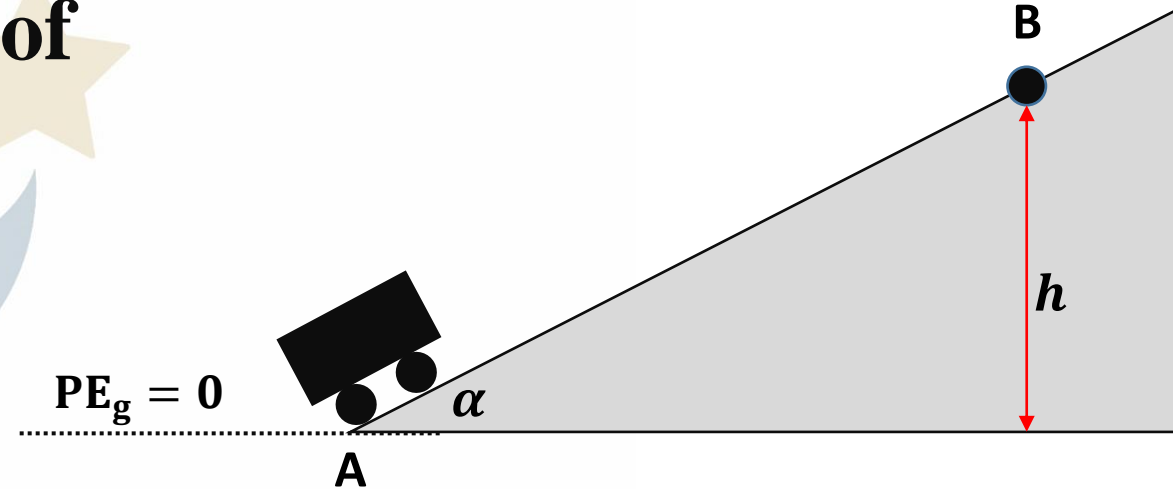
$$m = 500\text{kg}; V_A = 20\text{m/s}; \alpha = 30^\circ; AB = 35.1\text{m}; V_B = 7\text{m/s}$$

1. Calculate the mechanical energy of the system [car-earth] at point A.

$$ME_A = KE_A + PE_A$$

$$ME_A = \frac{1}{2}mV_A^2 + mgh_A$$

$$ME_A = \frac{1}{2} \times 500 \times (20)^2 + 0 \Rightarrow ME_A = 100,000\text{J}$$



Conservation of Mechanical Energy

$m = 500\text{kg}; V_A = 20\text{m/s}; \alpha = 30^\circ; AB = 35.1\text{m}; V_B = 7\text{m/s}$

2. Calculate the mechanical energy of the system [car-earth] at point B.

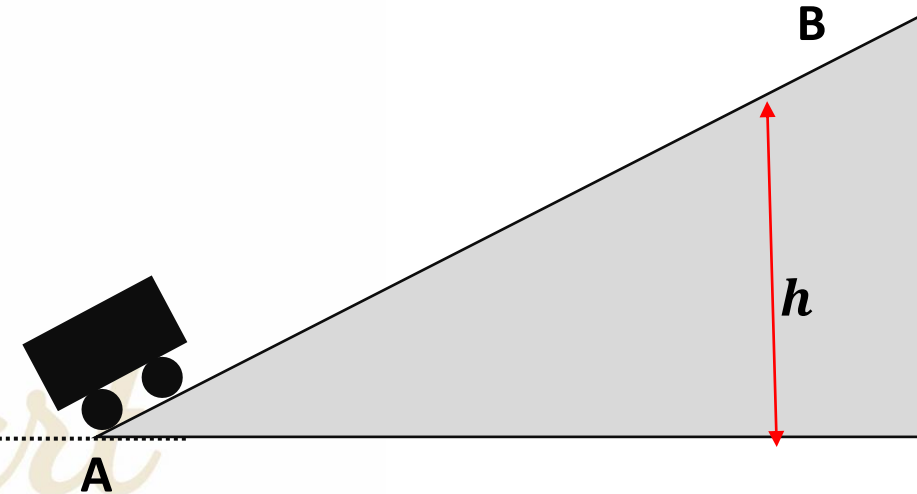
$$ME_B = KE_B + PE_B$$

→ $ME_B = \frac{1}{2}mV_B^2 + mgh_B$

$$ME_B = \frac{1}{2}mV_B^2 + mgAB \cdot \sin\alpha$$

$$\sin\alpha = \frac{h}{AB} \rightarrow h = AB \cdot \sin\alpha$$

$$ME_B = 0.5 \times 500 \times (7)^2 + 500 \times 10 \times 35.1 \times \sin 30 \quad ME_B = 100,000\text{J}$$



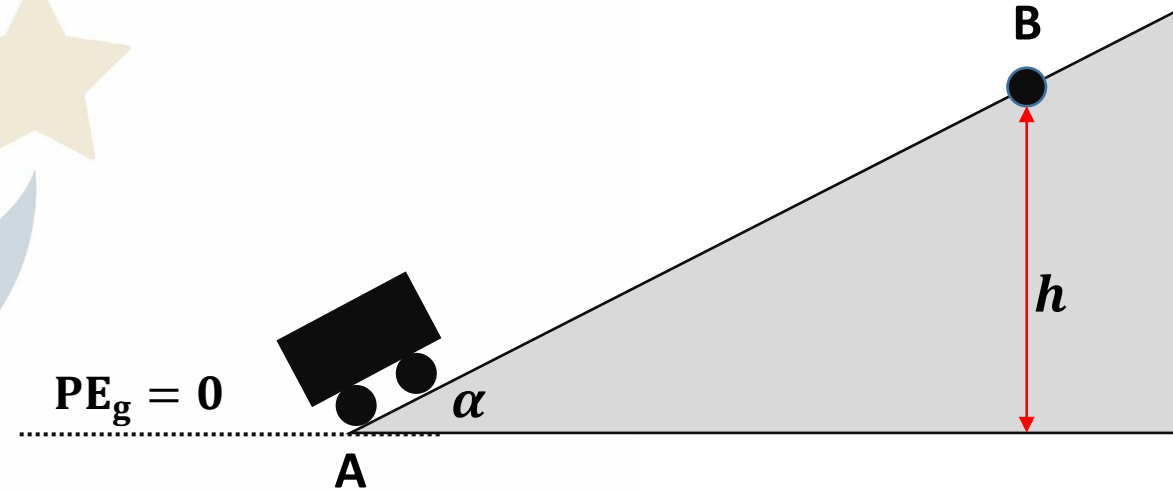
Conservation of Mechanical Energy

3. Compare the mechanical energy at A and B, then deduce.

$$ME_A = ME_B = 100,000J$$

Then the mechanical energy is conserved.

The frictional forces are neglected ($f_r = 0$).



Non – conservation of Mechanical Energy

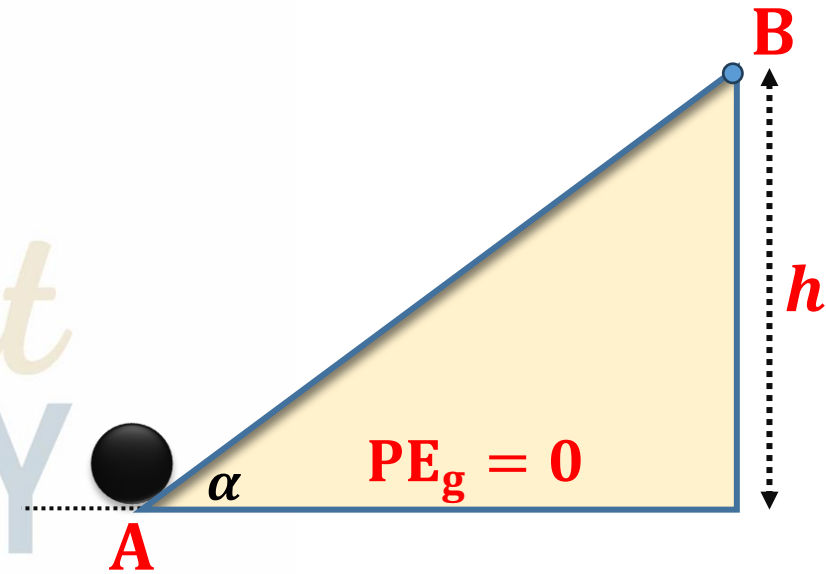
A particle moves from point **A** to point **B**. If the non-conservative forces acting on the body is not neglected, then:

The mechanical energy of the system[body-earth] is **NOT** conserved. ($f_r \neq 0$)

$$ME_A \neq ME_B$$

The variation of mechanical energy between these two points equal to sum of work done by these forces.

$$\Delta M.E = \sum W_{non-cons}$$





The work done by friction appears as a heat

The End

